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Orientation of a Dynamic Object with Resolution of Integer Ambiguities of the Second Differences of Pseudoranges by the Carrier Phase

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Abstract. Orientation of a dynamic object with resolution of integer ambiguities of the second differences of pseudoranges by the carrier phase is a rather complex task, requiring a significant initialization time for a given high confidence probability of ambiguity resolution. Involvement of rough measurements of inclinometers and the heading meter as a priori data makes it possible to significantly reduce the initialization time. To obtain highly accurate estimates, a Kalman-type filter is formed, the measurements of which are the Euler angles obtained from the former, using a priori data on the roll, pitch and heading from the specified sensors, and its algorithm is presented.

The modeling carried out by the authors showed the high efficiency of the proposed method for resolving phase ambiguities. The initialization time of the orientation system is practically zero at a confidence probability of 0.997. The standard deviation of the Euler angle estimate by the former with eight observed satellites is 0.003 radians. The Kalman-type filter proposed by the authors enables smoothing out of anomalous measurements and brings the orientation accuracy to 0.001 radians. The article's contents will be useful to specialists in the field of satellite navigation, geodesy and related disciplines.

Keywords: Euler angles, carrier phase pseudoranges, second differences of pseudoranges, resolution of phase ambiguities

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